

## DoP 23-24 - RESIT SOLUTIONS

1  $S$  is a smooth manifold of dim  $4-2=2$  if  $(0,1)$  is a regular value of  $\Phi$ . In fact in this case it is a 2D embedded submanifold of  $\mathbb{R}^4$ .

To be a regular value we need to check that  $D\Phi$  has maximal rank at all pts such that

$$\Phi(p) = (0,1)$$

$\Leftrightarrow$

$$\begin{cases} x^2 + y = 0 \\ x^2 + y + y^2 + z^2 + w^2 = 1 \end{cases} \iff \begin{cases} y = -x^2 \\ y^2 + z^2 + w^2 = 1 \end{cases}$$

$$D\Phi|_S = \begin{pmatrix} 2x & 1 & 0 & 0 \\ 2x & 2y+1 & 2z & 2w \end{pmatrix} \Big|_S = \begin{pmatrix} 2x & 1 & 0 & 0 \\ 2x & 1-2x^2 & 2z & 2w \end{pmatrix} \Big|_S$$

If  $x=y=0 \Rightarrow z^2+w^2=1$  and then either  $z$  or  $w$  or both are nonvanishing and

$\begin{pmatrix} 1 & 0 \\ 1 & 2z \end{pmatrix}$  or  $\begin{pmatrix} 1 & 0 \\ 1 & 2w \end{pmatrix}$  are minors with nonvanishing determinants (so rank 2)

$$\text{If } x \neq 0 \Rightarrow \det \begin{pmatrix} 2x & 1 \\ 2x & 1-2x^2 \end{pmatrix} = -4x^3 + 2x - 2x \\ = -4x^3 \neq 0$$

then rank = 2

Since  $D\Phi|_S$  has max rank 2 on  $S$ ,  $(0,1)$  is a regular value.

2.1.  $\tilde{x}, \tilde{y}$  are coordinates defined by the chart  $\varphi(x, y) = (x, x^3 + y)$  on  $\mathbb{R}^2$ . This is invertible by  $\varphi^{-1}(\tilde{x}, \tilde{y}) = (\tilde{x}, \tilde{y} - \tilde{x}^3)$  and  $\text{id}_{\mathbb{R}^2} \circ \varphi^{-1}$  is smooth thus is a smooth chart.

2.  $\frac{\partial}{\partial x}$  are vector fields defined locally by  $f \in C^\infty(U)$

$$\frac{\partial}{\partial x} \Big|_p \stackrel{F}{=} D(\text{id}_{\mathbb{R}^2} \circ \varphi^{-1}) \Big|_p e_1$$

$$\frac{\partial}{\partial \tilde{x}} \Big|_p \stackrel{F}{=} D(\varphi^{-1} \circ f) \Big|_p e_1$$

Since they pointwise act as derivations they define tangent vectors. By construction they map  $p \mapsto v_p \in T_p M$  & thus are sections of  $TM$ . Smoothness follows immediately by the construction.

3. One can use the change of variables rule

$$\frac{\partial}{\partial y_i} = \frac{\partial x_j}{\partial y_i} \frac{\partial}{\partial x_j}$$

↳ find

$$\begin{aligned} \frac{\partial}{\partial \tilde{x}} &= \frac{\partial x}{\partial \tilde{x}} \frac{\partial}{\partial x} + \frac{\partial y}{\partial \tilde{x}} \frac{\partial}{\partial y} = \frac{\partial \tilde{x}}{\partial \tilde{x}} \frac{\partial}{\partial x} + \frac{\partial (\tilde{y} - \tilde{x}^3)}{\partial \tilde{x}} \frac{\partial}{\partial y} \\ &= \frac{\partial}{\partial x} - 3\tilde{x} \frac{\partial}{\partial y} \end{aligned}$$

$$\frac{\partial}{\partial \tilde{y}} = \frac{\partial x}{\partial \tilde{y}} \frac{\partial}{\partial x} + \frac{\partial y}{\partial \tilde{y}} \frac{\partial}{\partial y} = \frac{\partial}{\partial y}$$

4. While  $\frac{\partial}{\partial \tilde{y}} \Big|_p = \frac{\partial}{\partial y} \Big|_p$  at all points,  $\frac{\partial}{\partial \tilde{x}} \Big|_{(1,0)} = \left( \frac{\partial}{\partial x} - 3 \frac{\partial}{\partial y} \right) \Big|_{(1,0)} \neq \frac{\partial}{\partial x} \Big|_{(1,0)}$

3. 1. It is known from linear algebra that  $\ker \sigma$  of a linear map is linear subspace, which is what the claim is proving. Otherwise they can explicitly follow the claim

2. Enough to show linear independence:  $aX + bY = 0$  iff  $a \partial_x = 0$  and  $b \partial_y = 0 \Rightarrow a = b = 0$

3.  $[X, Y] = Z$

4. Since  $\eta(Z) \cong 1$ ,  $Z_q \notin D_q \forall q \in \mathbb{R}$

4.1. If  $\Omega$  is the region bounded by  $\pi \circ \gamma$ , then  $\pi \circ \gamma = \partial \Omega$ . This is a line integral so we can use the fundamental theorem of calculus from the homework:

$$\int_{\gamma} \frac{1}{2} (x dy - y dx) = \int_I \frac{1}{2} (\gamma^1 \dot{\gamma}^2 - \gamma^2 \dot{\gamma}^1) dt$$

$$= \int_{\pi \circ \gamma} \frac{1}{2} (x dy - y dx) = \int_{\Omega} dx \wedge dy$$

integral independent on  $\gamma^3$ 
Stokes

2. Up to rescaling  $I = [0, 1]$ . Condition (a) reads

$$\dot{\gamma}^3 - \frac{1}{2} (\gamma^1 \dot{\gamma}^2 - \gamma^2 \dot{\gamma}^1) = 0 \quad \text{in } [0, t]$$

which can be integrated to yield (as the prev. pt)

$$\gamma^3(t) - \gamma^3(0) = \int_0^t \frac{1}{2} (\gamma^1 \dot{\gamma}^2 - \gamma^2 \dot{\gamma}^1) = \int_{\Delta_{[0,t]}} \frac{1}{2} (x dy - y dx)$$

3. follows from 2 by using 1 and setting  $t=1$

$$0 = \gamma^3(1) - \gamma^3(0) = \int_{\gamma} \frac{1}{2} (x dy - y dx) = \int_{\Omega} dx dy$$